

Dhruv Metha Ramesh

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EDUCATION	Rutgers University , New Brunswick, NJ, USA	
	Ph.D. in Computer Science	2022 – Present
	▪ Advisor: Abdeslam Boularias and Kostas E. Bekris	
	▪ Cumulative GPA: 3.92 / 4.0	
	Master of Science (M.S.) in Computer Science	2021 – 2022
	▪ Transferred to Ph.D.	
	B.M.S College of Engineering , Bengaluru, India	
	Bachelor of Engineering (B.E.) in Computer Science & Engineering	2015 – 2019
	▪ Cumulative GPA: 8.8 / 10.0	
WORK EXPERIENCE	Computer Science Dept, Rutgers University , New Brunswick NJ, USA	2022 – Present
	Instructor / Graduate Teaching Assistant	
	▪ CS560: Advanced Robotics	
	▪ CS440/520: Introduction to Artificial Intelligence	
	Leanovate Solutions , Bengaluru, India	2018 – 2020
	Software Engineer	
	▪ Indoor Navigation System: Developed a Bluetooth-based mobile app with occupancy detection for indoor navigation in commercial spaces.	
	▪ Front-End Lead: Led ReactJS development for a space management platform, enhancing room booking layouts, converting modules to PWA, and standardizing code practices.	
	▪ Reporting Tool Template Creator: Created an Excel Add-In using ReactJS that generates PDF reports via REST API integration.	
	▪ Client Presentations: Presented product releases to clients and stakeholders.	
PUBLICATIONS	UNDER REVIEW	
	[1] Dhruv Metha Ramesh , Aravind Sivaramakrishnan, Shreesh Keskar, Kostas E. Bekris, Jingjin Yu, Abdeslam Boularias, “PROBE: Proprioceptive Obstacle Detection and Estimation while Navigating in Clutter”,	
	[2] Isidoros Maroungkas*, Dhruv Metha Ramesh* , Joe H. Doerr, Edgar Granados, Aravind Sivaramakrishnan, Abdeslam Boularias, Kostas E. Bekris, “Integrating Model-based Control and RL for Sim2Real Transfer of Tight Insertion Policies”,	
	[3] Aravind Sivaramakrishnan, Sumanth Tangirala, Dhruv Metha Ramesh , Edgar Granados, and Kostas E. Bekris, “KRAFT: Sampling-Based Kinodynamic Replanning and Feedback Control over Approximate, Identified Models of Vehicular Systems ”.	
RELEVANT SKILLS	Python, C++, PyTorch, Robot Operating System (ROS), IsaacGym, MuJoCo, Stable Baselines3	
ROBOT SYSTEMS	KUKA LBR iiwa14, Unitree Go1, MuSHR	
CONFERENCE AND JOURNAL REVIEWING	▪ <i>Robotics: Science and Systems (R:SS)</i> - 2023-2024	
	▪ <i>IEEE International Conference on Robotics and Automation (ICRA)</i> - 2022-2024	
	▪ <i>IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)</i> - 2022-2023	
	▪ <i>Conference on Robot Learning (CoRL)</i> - 2024	
	▪ <i>Conference on Neural Information Processing Systems (NeurIPS)</i> - 2024	
	▪ <i>IEEE Robotics and Automation Letters (RA-L)</i>	